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(54) **Apparatus for automatically taking in smoke of rolled tobaccos and analysing the same**

Einrichtung zum automatischen Rauchen von Tabakrollen und zum Analysieren des Rauches

Appareil pour fumer automatiquement des rouleaux de tabac et pour l'analyse de la fumée

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Description

This invention relates to an apparatus for automatically taking in smoke of rolled tobaccos such as cigarettes or cigars and analyzing the same, a more particularly to an automatic smoke analyzing apparatus which can change, light and extinguish the rolled tobaccos automatically so as to eliminate all manual operation. EP-A-0 417 974 discloses an apparatus of the same kind having the features contained in the preamble of claim 1.

Upon manufacturing and selling rolled tobaccos such as cigarettes or cigars, the contents of chemical substances in tobacco smoke such as nicotine and tar must be indicated.

Like other agricultural products, the chemical properties of tobacco leaves are not accurately uniform. It is necessary, therefore, to sample rolled tobaccos at a predetermined rate with respect to the total number of the manufactured rolled tobaccos, in order to take the smoke of the sampled rolled tobaccos in the tobacco-smoke analyzing apparatus and analyze their chemical substances. As the number of the manufactured rolled tobaccos increases, the number of the rolled tobaccos to be sampled also increases.

Rolled tobaccos such as cigarettes and cigars are held by holders in a plurality of smoke inlets formed in the tobacco-smoke analyzing apparatus (hereinafter referred to only as the "analyzing apparatus"). After the rolled tobaccos have been lit, air is sucked in the analyzing apparatus through the rolled tobaccos mounted in the smoke inlets at a predetermined pattern. In each holder is provided a Cambridge filter for collecting tar or the like. The smoke taken in the analyzing apparatus is analyzed by an analyzing unit so as to find the contents of other chemical substances in the smoke.

With the conventional analyzing apparatus, mounting of rolled tobaccos and holders, lighting and extinguishing of the rolled tobaccos and the removal of tobacco ashes or tobacco ends including cigarette butts or cigar ends have been performed manually. For a great number of rolled tobaccos to be analyzed, the same simple operation must be repeated for a long time. This adds inspecting burden to the inspector.

In order to overcome the problem, it has been demanded that the full operation of the analyzing apparatus be automated. Since, however, rolled tobaccos are likely to be broken easily, it has been difficult to automatically light the rolled tobaccos mounted in the smoke inlets and automatically extinguish the rolled tobaccos securely after they have burnt to a predetermined portion.

The object of this invention is to provide an apparatus for automatically taking in smoke of rolled tobaccos and analyzing the smoke, which automatically mounts rolled tobaccos in the smoke inlets, lights and extinguishes the rolled tobaccos, and removes tobacco ashes or tobacco ends without the help of the inspector.

The apparatus according to this invention has a smoke analyzing device which automatically takes in smoke of rolled tobaccos such as cigarettes and analyzes the chemical contents of the smoke. The smoke analyzing device is provided with a plurality of smoke inlets, in each of which a rolled tobacco is mounted.

In the vicinity of the smoke analyzing device is provided mounting and demounting means for mounting and demounting rolled tobaccos in and from the smoke inlets. The mounting and demounting means comprises a universal operating robot which mounts rolled tobaccos in the smoke inlets and removes tobacco ashes or tobacco ends from the smoke inlets with the operating hand.

There are provided end position detecting means for detecting tips of rolled tobaccos and extinguishing position detecting means for detecting the position at which the rolled tobaccos are to be extinguished. The operating hand is provided with lighting means for lighting the tips of the rolled tobaccos and cutting-off means for cutting off the rolled tobaccos at the portions at which they are to be extinguished.

Such an apparatus for automatically analyzing smoke of rolled tobaccos not only can mount and demount rolled tobaccos in and from the smoke inlets but also can detect the positions of the tips of the rolled tobaccos, move them to lighting means, ensure to light them, cut off the rolled tobaccos at the portions to be extinguished and ensure to extinguish the rolled tobaccos. Therefore, the delicate operation which must have been relied on the operator with the conventional apparatus can be automated, and smoke analyzing of rolled tobaccos can be carried out fully automatically.

The preferred embodiment according to this invention is provided with means for automatically removing tobacco ashes and cut-off burnt portions of the rolled tobaccos and means for collecting and exhausting tobacco smoke such that the outer atmosphere of a room in which smoke analyzing is performed is retained clean and safety in the room is ensured as well.

This invention can be more fully understood from the following detailed description when taken in conjunction with the accompanying drawings, in which:

Fig. 1 is a front view of the overall automatic smoke analyzing device according to one embodiment of this invention;

Fig. 2 is a plan view of the over all automatic smoke analyzing device of Fig. 1;

Fig. 3 is a side view of the overall automatic smoke analyzing device of Fig. 1;

Fig. 4 is a side view of a smoking mechanism;

Fig. 5 is a plan view of a holding mechanism;

Fig. 6 is a front view of a cutting-off mechanism;

Fig. 7 is a view along line 7-7 in Fig. 6;

Fig. 8 is a general view illustrating the cutting-off operation of the cutting-off mechanism;

Fig. 9 is another general view illustrating the cutting-off operation of the cutting-off mechanism;

Fig. 10 is a perspective view of an extinguishing position detecting mechanism;

Fig. 11 is a longitudinal cross-sectional view of a detecting head;

Fig. 12 is a cross sectional view along line 12-12 in Fig. 11;

Fig. 13 is a general view illustrating the operation of the detecting head;

Fig. 14 is a general view illustrating the operation of the detecting head provided with a hood having a circular cross section;

Fig. 15 is a longitudinal cross sectional view of a conveyor mechanism;

Fig. 16 is a plan view of the conveyer mechanism;

Fig. 17 is a side view of a smoke exhausting mechanism; and

Fig. 18 is a cross sectional view along line 18-18 in Fig. 17.

This invention will be explained by way of the preferred embodiment with reference to the accompanying drawings.

Figs. 1 to 3 show one embodiment of the overall automatic analyzing device according to this invention. Fig. 1, Fig. 2 and Fig. 3 show its front view, its plan view and its side view, respectively.

The main body 1 of the automatic analyzing apparatus has a front plate 5 from which a plurality of smoke inlets 2 project. A holder 3 is provided on each smoke inlet 2 and mounts a rolled tobacco 4 such as a cigarette or a cigar in the smoke inlet 2.

As shown in Fig. 4, a smoking mechanism 11 is aligned with each smoke inlet 2 in the main body 1. Each smoking mechanism 11 is provided with a cylinder mechanism 13 which communicates with the respective smoke inlet 2 and a respective smoke collecting bag 15 through a three-way valve 12. The cylinder mechanism 13 is moved back and forth by a driving mechanism 14 at a predetermined period so as to make change-over of the three-way valve 12 according to the movement of the cylinder mechanism 14. Air is intermittently sucked in through a rolled tobacco 4 mounted in the respective smoke inlet 2, and the gas sucked in is delivered to the smoke collecting bag 15 through the three-way valve 15.

The smoke collecting bag 15 is connected to a suction pump 17 through a two-way valve 16. The smoke delivered to the smoke collecting bag 15 is sucked by the suction pump 17. A gas analyzing unit 18 is connected to the exhaust port of the suction pump 17.

A Cambridge filter is housed in each holder 3. Tar in the smoke of the rolled tobacco 4 is collected by the Cambridge filter and the other chemical substances are analyzed by a gas analyzing unit 18.

In front of the main body 1 is provided a moving mechanism 21 having a rail 22 disposed in parallel with the front plate of the main body 1. A moving table 23 is mounted on the rail 22 so as to be movable along it to an arbitrary position. On the moving table 23 are mounted

a tobacco loading table 24 for loading rolled tobaccos to be tested and a holder loading table 25 for loading holders 3.

On the moving table 23 is provided a robot 31 of a commercially available universal arm type having an articulated arm 32 as a rolled tobacco mounting and demounting device. An operating hand 33 is fixed to the distal end of the arm 32 by a shaft 34 so as to be rotatable about the shaft 34. The shaft 34 is rotatable in the vertical direction with respect to the arm 32.

From the operating hand 33 extend a holding mechanism 35 for holding rolled tobaccos, another holding mechanism 35' disposed at the position of the holder 3 and at another position, for holding a cutting-off mechanism 36 for cutting off the burnt portion of the rolled tobaccos and a lighting mechanism 37 for lighting the rolled tobaccos. These mechanisms extend perpendicularly to each other. In operation, the operating hand 33 rotates around the shaft 34, and the shaft 34 rotates with respect to the arm 32 such that the mechanisms, which are to operate, face the front plate of the main body 1.

Upon mounting rolled tobaccos in the smoke inlets 2, the robot 31 is operated such that the holder 3 on the holder loading table 25 is held by the holding mechanism 35' and is mounted in the corresponding smoke inlet 2, and then the rolled tobacco is held by the holding mechanism 35 and mounted on the holder 3.

Next, the rolled tobacco mounted on the holder 3 is lit by the lighting mechanism 37. The smoke of the rolled tobacco is taken in the smoking mechanism 11 at a predetermined mode, and then the smoke is analyzed.

In the vicinity of each smoke inlet 2 is provided an extinguishing position detecting mechanism 41 which has an infrared ray sensor. The infrared ray sensor detects the infrared rays radiated from the burning portion of the rolled tobacco at which the rolled tobacco is to be extinguished.

Then, the robot 31 is operated such that the holding mechanism 35' of the operating hand 35 holds the cutting-off mechanism 36 which is located at the different position. The burnt portion of the rolled tobacco is cut off by the cut-off mechanism 36 and the rolled tobacco is extinguished. The smoking mechanism 11 continues its operation so as to suck in all smoke retained in the extinguished rolled tobacco.

After the cutting-off, the robot 31 is operated such that the holding mechanism 35 faces the front plate 5 of the main body 1 and then holds the tobacco ashes or tobacco end and pull it off. The process beginning with the mounting of rolled tobacco 4 and ending with the removal of tobacco ashes or a tobacco end is repeated five times, and then the holder 3 is removed from the smoke inlet 2 by the holding mechanism 35'.

The robot 31 is moved again by means of the moving mechanism 21 so as to be disposed in front of the next smoke inlet 2 and the same process as the above-mentioned is repeated. This process automatically con-

tinues until the process at the final smoke inlet 2 is completed.

There will be described a unit used in the automatic smoke analyzing device, for detecting the accurate position of the tip ends of the rolled tobaccos mounted in the smoke inlets 2 and for ensuring the lighting of the tips of the rolled tobaccos.

As shown in Fig. 5, the holding mechanism 35 of the operating hand 33 has a pair of fingers 71 closed and opened by means of a driving mechanism 72 with the fingers 71 maintained parallel to each other. When the fingers 71 are closed, they hold a rolled tobacco.

An optical detector comprises light source 73 such as an LED provided in the forward end portion of one of the fingers 71 and a photodiode 74 provided in the forward end portion of the other finger 71 opposed to the light source 71. Light emitted from the light source 73 is received by the photodiode 74. When an object, i.e., a rolled tobacco exits between the fingers 71, i.e., between the light source 73 and the photodiode 74, the light from the light source 73 is interrupted by the rolled tobacco.

After mounted a rolled tobacco 4 in the respective inlet 2 with the fingers 71 opened, the robot 31 is operated so as to place the rolled tobacco 4 between the fingers 71 and then moves the holding mechanism 35 in the axial direction of the rolled tobacco 4. When the light source 73 and the photodiode 74 face an intermediate portion of the rolled tobacco 4, the light from the light source 73 is interrupted by the rolled tobacco 4 and thus the photodiode 74 does not detect the light. As the holding mechanism 35 is further moved and the light source 73 and the photodiode 74 exceed the tip of the rolled tobacco 4, the light from the light source 73 is incident on the photodiode 74, whereby the tip of the rolled tobacco 4 is detected.

The robot 31 memorizes the position of the tip of the rolled tobacco 4 in this state. Then, the heater of the lighting mechanism 37 attached to the operating hand 33 is directed so as to face the front plate of the main body 1. The heater of the lighting mechanism 37 is moved to a position closed to the tip of the rolled tobacco 4 and lights the same. In this case, the movement of the lighting mechanism 37 is controlled according to the information on the position of the tip of the tobacco 4. The heater move to a position closed to the tip of the rolled tobacco 4 so as to light the same securely. The heater can be prevented from abutting against the tip of the rolled tobacco 4 so strongly that the rolled tobacco 4 is displaced from the heater.

The rolled tobacco 4 is burnt from its tip to a predetermined intermediate portion (i.e., the extinguishing position) separated from the tip position as a datum position by a predetermined length.

An extinguishing position detecting mechanism 41 can be set at the extinguishing position of the rolled tobacco. When the burning of the rolled tobacco 4 which has started at its tip arrives at the extinguishing position, the extinguishing position detecting mechanism 41

detects it, and the rolled tobacco 4 is cut off at the extinguishing position by the cutting-off mechanism 36. Then, the rolled tobacco 4 stops burning.

The cutting-off mechanism 36 will be described with reference to Fig. 6. The cutting-off mechanism 36 is provided with a pair of chucking members 81 which project from the operation hand 33 and are moved toward and away from each other by means of an opening and closing mechanism (not shown) provided on the operating hand 33. An opening and closing member 82 is removably connected to the front portion of each chucking member 81. The opening and closing members 82 are movable toward and away from each other together with the respective chucking members 81. Two slide bushes 85 are formed in the lower portion of each opening and closing member 82. Two guide rods 83 are slidably inserted in the slide bushes 85 of both opening and closing members 82 such that the guide rods 83 allow for the accurate movement of the opening and closing members 82. Between both opening and closing members 82 is disposed a compression coil spring 84 for urging the opening and closing members 82 so as to be separated from each other.

A pair of thin plate-like cutting blades 86 are connected by bolts 87 to the forward ends of the opening and closing members 82 so as to be opposed to and extend toward each other and to be replaced easily by removing the bolts 87. The forward portion of each cutting blade 86 has a triangular form such as an isosceles triangular shape whose apex is directed toward the other cutting blade 86 and whose both sides adjacent to the apex form cutting edges. The apexes of both cutting blades 86 are disposed opposed to each other. One of the cutting blades 86 is displaced by a thickness of each cutting blade from the other cutting blade 86 in the direction of its thickness. As the opening and closing members 82 approach each other, the forward portions of the triangular cutting blades 86 come to overlap each other.

With the opening and closing members 82 separated, the cutting-off mechanism 36 is moved to the position at which a rolled tobacco 4 to be cut is placed, and the rolled tobacco 4 is disposed between the two opening and closing members 82. Thereafter, the cutting-off mechanism 36 is moved in the axial direction of the rolled tobacco to the position at which the cutting blades 86 cut off the rolled tobacco 4, i.e., slightly behind the extinguishing position of the rolled tobacco 4.

As the chucking members 81 are moved toward each other by the opening and closing mechanism, the opening and closing members 82 as well as the cutting blades 86 approach each other. As shown in Fig. 8, the apexes of the cutting blades 86 are stuck in the rolled tobacco 4 at two opposed lateral sides thereof. As the cutting blades 86 further approach each other, the cutting edges formed on the inclined sides of the triangular cutting blades 86 gradually cut the rolled tobacco 4. The cutting blades 36 advance further and overlap each

other to cut off the rolled tobacco 4 completely, as shown in Fig. 9. After the burnt part of the rolled tobacco 4 has been cut off, the rolled tobacco is extinguished.

The smoking mechanism 11 is operated for a predetermined time after the cutting-off and extinction of the rolled tobacco 4 so as to take in smoke still remaining in the residual portion of the rolled tobacco 4 and analyze the taken-in smoke.

There will be described the extinguishing position detecting mechanism 41 which detects infrared rays radiated from the rolled tobacco when the rolled tobacco is burnt to the extinguishing position. Upon sensing the infrared rays from the rolled tobacco, the mechanism 41 moves the cutting-off mechanism 36.

The extinguishing position detecting mechanism 41 has a detecting head 91 disposed slantwise below the smoke inlets 2 and connected to the forward end of a rod 92. The detecting head 91 can be reciprocated and rotated by a head moving mechanism 90. The rod 92 extends horizontally through the front plate 5 of the main body 1 and is rotatably and slidably supported by a bearing 93 provided on the front plate 5.

Within the main body 1 is provided a rotary actuator 95 to which is connected a cylindrical sleeve 96 formed with a pair of diametrically opposed and axially extending slits 97. Diametrically opposed pins 98 extend perpendicularly outward from the rear end portion of the rod 92. The rear end portion of the rod 92 is inserted in the sleeve 96 with the pins 98 engaged with the slits 97. Thus, the rod 92 and the detecting head 91 are rotated by the rotary actuator 95.

In the main body 1 is provided a moving member 99 which is engaged by one of the pins 98 of the rod 92 and reciprocated axially of rod 92 by means of an actuator (not shown). As the rod 92 reciprocates axially, the detecting head 91 also moves back and forth.

As shown in Figs. 11 and 12, the detecting head 91 has a housing 101 and 102 which are assembled together with an O-ring interposed therebetween. In the housings 101 and 102 is mounted an infrared ray sensor 104 comprising an infrared-ray detecting element such as a Ge photodiode having a high sensitivity for infrared rays of short wavelengths emitted from the extinguishing position of the rolled tobacco.

Formed in the housing 101 is an opening 106 through which infrared rays enter the infrared ray sensor 104. A hood 107 having a semicircular cross section extends outward from the opening 106 and is arranged such that the arcuated surface of the hood 107 is directed forward, i.e., toward the tip of the rolled tobacco and the edges thereof is directed rearward, i.e., toward the rear end of the rolled tobacco.

The operation of the extinguishing position detecting mechanism 41 will be described.

First, the extinguishing position detecting mechanism 41 is retracted. The moving member 99 pushes out the rod 92 through the pin 98, thereby advancing the detecting head 91 by several centimeters. Then, the moving member 99 returns to the starting position so as

to allow the detecting head 91 to move back and forth freely. The rod 92 is rotated such that the hood 107 of the detecting head 91 takes a horizontal posture. In this way, the detecting head 91 is prevented from interfering with the arm 32 of the robot 31, the holding mechanism 35, etc. upon mounting of the holder 3 and a rolled tobacco 4.

After a rolled tobacco 4 has been mounted and the tip of the rolled tobacco has been detected by the device for detecting the position of the tip of the rolled-tobacco (the end position detecting means), the extinguishing position of the rolled tobacco, i.e., the length between the tip of the rolled tobacco and the portion of the rolled tobacco to be extinguished is calculated, by making the position of the detected tip of the rolled tobacco as the datum position. The detecting head 91 advances and the rod 92 is rotated so as to direct the hood 107 of the detecting head 91 in the slantwise upper direction, i.e., toward a lateral side of the rolled tobacco. The hood 107 of the detecting head 91 is placed by the arm 32 of the robot 31 at the extinguishing position. Thereafter, the rolled tobacco is lit and burning starts.

The rolled tobacco 4 continues to be burnt and the burning portion arrives at a black line indicating the extinguishing position. Infrared rays having a relatively short wavelength radiated from the extinguishing position of the rolled tobacco 4 enter the infrared ray sensor 104. The infrared ray sensor 104 detects them and sends output signals to the robot 31. In response to the output signals, the rod 92 is rotated to make the hood 107 take a substantially horizontal position, whereby the hood 107 is prevented from interfering with the arm 32 of the robot 31 and the cutting-off mechanism 36 of the operating hand 33. In response to the output signals, the robot 31 is further operated to make the cutting-off mechanism 36 cut off the rolled tobacco 4 at its extinguishing position, thereby extinguishing the rolled tobacco 4.

The hood 107 of the detecting head 91 has a semi-circular cross section. This improves the detecting accuracy of the extinguishing position of the rolled tobacco 4, as explained below.

As shown in Fig. 13, infrared rays are radiated from all the extinguishing positions of the rolled tobacco in all directions. Out of the infrared rays coming from all the burning portions, the hood 107 allows only the ones radiated from the portion of the rolled tobacco 4 on and in the vicinity of the black line (the extinguishing position) to enter the infrared ray sensor 104 but prevents the infrared rays radiated from the portions away from its black line (i.e., the extinguishing position) from entering the infrared ray sensor 107.

If the hood 107a has a circular cross section as shown in Fig. 14, oblique rays from a portion of the rolled tobacco 4 which is close to its extinguishing position between the tip of the rolled tobacco 4 and its extinguishing position arrive at the forward end of the hood 107a. Such rays which entered the interior of the forward end of the hood 107a are repeatedly reflected on

the inner surface of the hood 107a and reach the infra-red ray sensor 104. However, such internal reflection does not occur on the hood 107 having a semicircular cross section. The smoking mechanism 11 continues to operate for a predetermined time after the rolled tobacco 4 has been cut off at the extinguishing position, and the smoke remaining in the unburnt portion of the rolled tobacco 4 is sucked in the smoking mechanism 11. Then, the smoke is analyzed and the analyzing result is improved.

The automatic analyzing apparatus according to this invention is provided with a treating unit for exhausting tobacco ashes and tobacco ends, which will be described with reference to Figs. 15 and 16.

The smoke inlets 2 are arranged horizontally in the front plate of the main body 1. Under the smoke inlets 2 is provided a horizontal conveyer mechanism 51 which has, on its both ends, a pair of rollers 52 around which a belt 53 is wound. The rollers 52 are rotated by a driving mechanism (not shown) to drive the belt 53 horizontally, as shown by the arrow in Fig. 5.

The belt 53 is made of heat-resistive material such as a thin metal plate (stainless steel, for example) and has a width sufficiently larger than the length of rolled tobaccos as shown in Fig. 16. The belt 53 may be made of heat-resistive synthetic resin instead of metal.

An ash container 55 is disposed under the distal end portion of the conveyer mechanism 51. Tobacco ashes 54 and/or tobacco ends dropped on the belt 53 of the conveyer mechanism 51 are transported horizontally by the running belt 53 and fall into the ash container 55.

It is preferred that the conveyer mechanism 52 is operated only after ashes of the cut-off burnt portions of the rolled tobaccos have been removed from the smoke inlets 2 and dropped on the belt 53, such that the dropped burnt portions and/or tobacco ashes are immediately transported to the ash container 55 for their disposal.

Since the dropped tobacco ashes and tobacco ends are immediately transported to the ash container 55 by the conveyer mechanism 51, the smoke rising from the tobacco ashes and the tobacco ends does not enter other rolled tobaccos. This prevents adverse effects on the analyzing results and facilitates an accurate chemical analysis.

In this embodiment, the belt 53 is made of metallic material such as stainless steel. Since, therefore, the belt 53 has a high heat conductivity, heat produced from the dropped tobacco ashes, etc. is dissipated easily and is ensured to be extinguished in a short time.

As shown in Fig. 17 and 18, a smoke exhausting mechanism 60 is provided above the smoke inlets 2. The mechanism 60 is provided with a generally cylindrical smoke exhausting hood 61. The hood 61 has an opening at its lower end and is provided on its upper end with a small fan 63. Auxiliary smoke collected by the smoke exhausting hood 61 is sent upward by the fan 63 to the outer atmosphere of the test room through a

smoke exhausting duct 69 (shown in Fig. 3) provided in the vicinity of the ceiling of the test room.

The smoke exhausting hood 61 is moved upward and downward by means of a hood lifting mechanism 62 comprising an air cylinder unit 68 which is fixed substantially vertically by means of a fixture 64 to the front plate 5 of the main body 1 of the smoke analyzing device. The piston rod 65 extending downward from the lower end of the air cylinder unit has the lower end fixed to the smoke exhausting hood 61 by a fixture 66.

The hood 61 moves together with fan 63 when the holders 3 and rolled tobaccos 4 mounted in the smoke inlets 2, the rolled tobaccos 4 are lit and cut off, and the tobacco ashes and/or tobacco ends are removed. Thus, the smoke exhausting hood 61 does not interfere with the arm 32 of the robot 31 and the operating hand 33.

While the smoke of the rolled tobaccos 4 is being sucked in the automatic smoke analyzing device, the smoke exhausting hood 61 is lowered by the hood lifting mechanism 62 to the vicinity of the rolled tobaccos 4 held in the smoke inlets 2 as shown by the two-dot chain lines in Figs. 17 and 18. In consequence, the air flow around the smoke inlets 4 is controlled to take a predetermined stable state and smoke analysis is performed in a predetermined controlled state.

Since the fan 63 guides auxiliary smoke collected by the smoke exhausting hood 61 upward to the smoke exhausting duct, it is unnecessary to use a flexible smoke exhausting hose for connecting the smoke exhausting hood 61 to the smoke exhausting duct in this invention. This simplifies the structure of the apparatus and facilitates its maintenance.

Claims

1. An apparatus for automatically taking in smoke of rolled tobaccos and automatically analyzing the smoke, comprising:
 - a main body (1) having a plurality of smoke inlets (2) having rolled tobaccos (4) mounted therein, for taking in smoke generated by said rolled tobaccos and analyzing chemical contents of said smoke;
 - mounting and demounting means (31), each provided at a respective one of said smoke inlets (2), for mounting one of said rolled tobaccos (4) in said one of said smoke inlets and demounting said one of said rolled tobaccos from said one of said smoke inlets;
 - end position detecting means (73, 74) for detecting tip positions of said rolled tobaccos mounted in said smoke inlets;
 - extinguishing position detecting means (41) for detecting extinguishing positions of said rolled tobaccos which are burning in said smoke inlets;
 - cutting-off means (36) for cutting off burnt portions from said rolled tobaccos at said extinguishing positions and extinguishing said rolled tobaccos;
 - characterized by lighting means (37) for lighting-tips of

- said rolled tobaccos mounted in said smoke inlets; wherein said lighting means (37) moved to said forward ends of said rolled tobaccos which have detected by said end position detecting means (73, 74) so as to light said tips of said rolled tobaccos, said extinguishing position detecting means detect said extinguishing positions, and said cutting-off means to cut off said burnt portions.
2. The apparatus according to claim 1, characterized in that said operating means comprises a universal operating robot (31) having an operating hand (33) carrying said end position detecting means (73, 74), said lighting means (37) and said cutting-off means (36).
 3. The apparatus according to claim 2, characterized in that said end position detecting means has optical detecting means (73, 74) mounted on said operating hand (33) of said operating robot (31) and moved axially of said rolled tobaccos (4) mounted in said smoke inlets (2) as said operating hand (33) is moved, for detecting said tips of said rolled tobaccos.
 4. The apparatus according to claim 3, characterized in that said operating hand (33) of said operating robot (31) has a pair of openable fingers (71) for holding said rolled tobaccos (4) and is operated so as to dispose said rolled tobacco (4) between said fingers (71), and said optical detecting means comprises a light source (73) provided in one of said fingers (71) and an optical detecting element (74) provided in the other finger (74), for detecting light from said light source, said optical detecting means being arranged such that said light from said light source is interrupted by said rolled tobacco (4) when said rolled tobacco is disposed between said fingers and said optical detecting element (74) detects said light from said light source (73) to sense said tip of said rolled tobacco when said tip of said rolled tobacco passes beyond said light detecting element by as said operating hand moves along said rolled tobacco.
 5. The apparatus according to claim 1, characterized in that said extinguishing position detecting means (41) includes a detecting head (91) provided at a position in a vicinity of said smoke inlet (2) and movable between said position and a predetermined axial position of said rolled tobacco (4), said detecting head (91) comprising an infrared ray sensor (104), and said extinguishing position detecting means further includes a hood (107) projecting toward a predetermined position of a lateral side of said rolled tobacco, for preventing infrared rays emitted from the other portion of said rolled tobacco than a portion at said extinguishing position and in

a vicinity thereof from entering said detecting head (91).

6. The apparatus according to claim 5, characterized in that said hood (107) has a substantially semi-circular cross section with a semicircular surface thereof facing said tip of said rolled tobacco (4).
7. The apparatus according to claim 2, characterized in that said cutting means (36) has a pair of opening and closing members (32) provided on said operating hand (33) of said operating robot (31), each of said opening and closing members (32) including a cutting blade (86) having a triangular forward portion which extends toward the other opening and closing member and is defined by an apex and two side edges on both sides of said apex, said apex of said one of said opening and closing members being arranged opposed to said apex of said other opening and closing member, said triangular forward portions of said opening and closing members being arranged to overlap with each other, as said opening and closing members approach each other.
8. The apparatus according to claim 1, characterized in that ash exhausting means (51, 52, 53, 55) is provided under said smoke inlets (2) and comprises a conveyer mechanism (51) having a horizontally running heat-resistive belt (53) and an ash container (55) provided under a distal end portion of said conveyer mechanism, for receiving tobacco ashes and tobacco ends transported by said conveyer mechanism.
9. The apparatus according to claim 8, characterized in that said belt (53) is made of a thin metal plate.
10. The apparatus according to claim 1, characterized in that smoke exhausting means (60) is provided in a vicinity of said main body (1) and comprises a smoke exhausting hood (61) provided above said smoke inlets (2), for collecting auxiliary smoke rising from said rolled tobaccos mounted in said smoke inlets and burning, a fan (63) for moving said auxiliary smoke collected in said smoke exhausting hood (61) upward, and a hood lifting mechanism (62) for moving said smoke exhausting hood vertically.

Patentansprüche

1. Vorrichtung zum automatischen Eintragen von Rauch von gerollten Tabakerzeugnissen und zum automatischen Analysieren des Rauchs, umfassend:
einen Hauptkörper (1) mit einer Mehrzahl von Raucheinlässen (2), in denen die gerollten Tabakerzeugnisse (4) angebracht sind, um Rauch einzu-

tragen, der durch die gerollten Tabakerzeugnisse erzeugt wird, und um den chemischen Gehalt des Rauchs zu analysieren;

Anbring- und Abnahmeeinrichtungen (31), von denen jeweils eine an einem jeweiligen der Raucheinlässe (2) vorgesehen ist, um eines der gerollten Tabakerzeugnisse (4) in dem einen der Raucheinlässe anzubringen und das eine gerollte Tabakerzeugnis von dem einen der Rauchauslässe abzunehmen; eine Endpositionsermittlungseinrichtung (73, 74) zum Ermitteln von Spitzenpositionen der gerollten Tabakerzeugnisse, die in den Raucheinlässen angebracht sind;

eine Ausmach-Positionsermittlungseinrichtung (41) zum Ermitteln von Ausmach-Positionen der gerollten Tabakerzeugnisse, die in den Raucheinlässen abgebrannt werden; eine Abschneideeinrichtung (36) zum Abschneiden abgebrannter Abschnitte von den gerollten Tabakerzeugnissen an den Ausmach-Positionen und zum Ausmachen der gerollten Tabakerzeugnisse;

gekennzeichnet durch

eine Anzündeinrichtung (37) zum Anzünden der Spitzen der gerollten Tabakerzeugnisse, die in den Raucheinlässen angebracht sind;

wobei die Anzündeinrichtung (37) zu den Vorderenden der gerollten Tabakerzeugnisse bewegt werden, die durch die Endpositionsermittlungseinrichtung (73, 74) ermittelt wurden, um die Spitzen der gerollten Tabakerzeugnisse anzuzünden, wobei die Ausmach-Positionsermittlungseinrichtung die Ausmach-Positionen ermittelt, und wobei die Abschneideeinrichtung die abgebrannten Abschnitte abschneidet.

2. Vorrichtung nach Anspruch 1, dadurch gekennzeichnet, daß die Betätigungseinrichtung einen universellen Betätigungsroboter (31) umfaßt, der eine Betätigungshand (33) aufweist, welche die Endpositionsermittlungseinrichtung (73, 74), die Anzündeinrichtung (37) und die Abschneideeinrichtung (36) trägt.
3. Vorrichtung nach Anspruch 2, dadurch gekennzeichnet, daß die Endpositionsermittlungseinrichtung eine optische Ermittlungseinrichtung (73, 74) aufweist, die auf der Betätigungshand (33) des Betätigungsroboters (31) angebracht und axial zu den gerollten Tabakerzeugnissen (4) bewegt wird, die in den Raucheinlässen (2) angebracht sind, wenn die Betätigungshand (33) zum Ermitteln der Spitzen der gerollten Tabakerzeugnisse bewegt wird.
4. Vorrichtung nach Anspruch 3, dadurch gekennzeichnet, daß die Betätigungshand (33) des Betätigungsroboters (31) ein Paar von aufmachbaren Fingern (71) zum Halten der gerollten Tabakerzeugnisse (4) aufweist und so betätigt wird, das das

gerollte Tabakerzeugnis (4) zwischen den Fingern (71) angeordnet wird und die optische Ermittlungseinrichtung eine Lichtquelle (73) aufweist, die in einem der Finger (71) vorgesehen ist, und ein optisches Ermittlungselement (74), das in dem anderen Finger (74) vorgesehen ist, um Licht von der Lichtquelle zu ermitteln, wobei die optische Ermittlungseinrichtung derart angeordnet ist, daß das Licht von der Lichtquelle durch das gerollte Tabakerzeugnis (4) unterbrochen wird, wenn das gerollte Tabakerzeugnis zwischen den Fingern angeordnet ist, und das optische Ermittlungselement (74) das Licht von der Lichtquelle (73) ermittelt, um die Spitze des gerollten Tabakerzeugnisses zu ermitteln, wenn die Spitze des gerollten Tabakerzeugnisses über das Lichtelement hinausläuft, wenn die Betätigungshand sich entlang dem gerollten Tabakerzeugnis bewegt.

5. Vorrichtung nach Anspruch 1, dadurch gekennzeichnet, daß die Ausmach-Positionsermittlungseinrichtung (41) einen Ermittlungskopf (91) enthält, der in einer Position im Umfeld des Raucheinlasses (2) vorgesehen und zwischen der Position und einer vorbestimmten axialen Position des gerollten Tabakerzeugnisses (4) beweglich ist, wobei der Ermittlungskopf (91) einen Infrarotstrahlensensor (104) umfaßt, und die Ausmach-Positionsermittlungseinrichtung ferner eine Haube (107) aufweist, die zu einer vorbestimmten Position der lateralen Seite des gerollten Tabakerzeugnisses vorsteht, um zu verhindern, daß Infrarotstrahlen, die von einem anderen Abschnitt des gerollten Tabakerzeugnisses als einen Abschnitt in der Ausmach-Position und in einem Umfeld davon emittiert werden in den Ermittlungskopf (91) eintreten.
6. Vorrichtung nach Anspruch 5, dadurch gekennzeichnet, daß die Haube (107) einen im wesentlichen halbkreisförmigen Querschnitt aufweist, wobei eine Halbkreisoberfläche davon der Spitze des gerollten Tabakerzeugnisses (4) gegenüberliegt.
7. Vorrichtung nach Anspruch 2, dadurch gekennzeichnet, daß die Schneideinrichtung (36) ein Paar Öffnungs- und Schließelemente (32) aufweist, die auf der Betätigungshand (33) des Betätigungsroboters (31) vorgesehen sind, wobei jedes der Öffnungs- und Schließelemente (32) eine Schneidklinge (86) enthält, die einen dreieckigen vorderen Abschnitt aufweist, der sich zu dem anderen Öffnungs- und Schließelement erstreckt und durch eine Spitze festgelegt ist und zwei Seitenkanten auf beiden Seiten der Spitze, wobei die Spitze der einen der Öffnungs- und Schließelemente gegenüberliegend zur Spitze des anderen Öffnungs- und Schließelements angeordnet ist, wobei die dreieckigen vorderen Abschnitte der Öffnungs-

und Schließelemente so angeordnet sind, daß sie einander überlappen, wenn sich die Öffnungs- und Schließelemente einander nähern.

8. Vorrichtung nach Anspruch 1, dadurch gekennzeichnet, daß eine Ascheabföhreinrichtung (51, 52, 53, 55) unter den Raucheinlässen (2) vorgesehen ist und einen Förderermechanismus (51) umfaßt, der ein horizontal laufendes wärmebeständiges Band (53) und einen Aschebehälter (55) aufweist, der unter einem entfernten Endabschnitt des Förderermechanismus angeordnet ist, um Tabakasche und Tabakenden aufzunehmen, die durch den Förderermechanismus transportiert werden.
9. Vorrichtung nach Anspruch 8, dadurch gekennzeichnet, daß das Band (53) aus einer dünnen Metallplatte hergestellt ist.
10. Vorrichtung nach Anspruch 1, dadurch gekennzeichnet, daß eine Rauchabföhreinrichtung (60) im Umfeld des Hauptkörpers (1) vorgesehen ist und eine Rauchabföhrraube (61) aufweist, die über den Raucheinlässen (2) vorgesehen ist, um zusätzlichen Rauch zu sammeln, der von den gerollten Tabakerzeugnissen aufsteigt, die in den Raucheinlässen angebracht sind und abbrennen, und ein Gebläse (63) zum Bewegen des zusätzlichen Rauchs, der in der Rauchabföhrraube (61) gesammelt wird, in Aufwärtsrichtung, und einen Haubenhubmechanismus (62) zum Bewegen der Rauchabföhrraube in vertikaler Richtung.

Revendications

1. Appareil pour prélever automatiquement de la fumée de rouleaux de tabac et analyser automatiquement la fumée, comprenant :
 - un corps principal (1) ayant une pluralité de bouches à fumer (2) ayant des rouleaux de tabac (4) montés à l'intérieur, pour prélever la fumée produite par lesdits rouleaux de tabac et analyser le contenu chimique de ladite fumée ;
 - des moyens de montage/démontage (31), prévus chacun au niveau d'une bouche respective parmi lesdites bouches à fumer (2), pour monter l'un desdits rouleaux de tabac (4) dans ladite bouche à fumer et démonter l'un desdits rouleaux de tabac depuis ladite bouche à fumer ;
 - des moyens de détection de position d'extrémité (73, 74) pour détecter des positions d'extrémité desdits rouleaux de tabac montés dans lesdites bouches à fumer ;
 - des moyens de détection de position d'extinction (41) pour détecter des positions d'extinction desdits rouleaux de tabac qui sont en train de brûler dans lesdites bouches à fumer ;

- des moyens de découpe (36) pour découper des parties brûlées depuis lesdits rouleaux de tabac auxdites positions d'extinction et pour éteindre lesdits rouleaux de tabac ; caractérisé par :
- des moyens d'allumage (37) pour allumer les extrémités desdits rouleaux de tabac montés dans lesdites bouches à fumer ;
- dans lequel lesdits moyens d'allumage (37) sont déplacés jusqu'auxdites extrémités avant desdits rouleaux de tabac qui ont été détectées par desdits moyens de détection de position d'extrémité (73, 74) de manière à allumer lesdites extrémités desdits rouleaux de tabac, lesdits moyens de détection de position d'extinction détectant lesdites positions d'extinction, et lesdits moyens de découpe étant destinés à découper lesdites parties brûlées.

2. Appareil selon la revendication 1, caractérisé en ce que lesdits moyens de fonctionnement comprennent un robot à fonctionnement universel (31) ayant une main de manipulation (33) qui porte lesdits moyens de détection de position d'extrémité (73, 74), lesdits moyens d'allumage (37) et lesdits moyens de découpe (36).

3. Appareil selon la revendication 2, caractérisé en ce que lesdits moyens de détection de position d'extrémité comprennent des moyens de détection optiques (73, 74) montés sur ladite main de manipulation (33) dudit robot de fonctionnement (31) et déplacés axialement par rapport auxdits rouleaux de tabac (4) montés dans lesdites bouches à fumer (2) tandis que ladite main de manipulation (33) est déplacée, pour détecter lesdites extrémités dudit rouleau de tabac.

4. Appareil selon la revendication 3, caractérisé en ce que ladite main de manipulation (33) dudit robot de fonctionnement (31) comporte une paire de doigts susceptibles d'être ouverts (71) pour maintenir lesdits rouleaux de tabac (4) et en ce qu'elle est mise en fonctionnement de manière à disposer ledit rouleau de tabac (4) entre lesdits doigts (71), et lesdits moyens de détection optiques comprennent une source lumineuse (73) prévue dans l'un desdits doigts (71) et un élément de détection optique (74) prévu dans l'autre doigt (74), pour détecter la lumière depuis ladite source lumineuse, lesdits moyens de détection optiques étant agencés de telle manière que ladite lumière provenant de ladite source lumineuse est interrompue par ledit rouleau de tabac (4) lorsque ledit rouleau de tabac est disposé entre lesdits doigts et que l'élément de détection optique (74) détecte ladite lumière provenant de ladite source lumineuse (73) pour détecter ladite extrémité dudit rouleau de tabac lorsque ladite

extrémité dudit rouleau de tabac passe au-delà dudit élément de détection de lumière lorsque ladite main de manipulation se déplace le long dudit rouleau de tabac.

5. Appareil selon la revendication 1, caractérisé en ce que lesdits moyens de détection de position d'extinction (41) comprennent une tête de détection (91) prévue à une position au voisinage de ladite bouche à fumer (2) et mobile entre ladite position et une position axiale prédéterminée dudit rouleau de tabac (4), ladite tête de détection (91) comprenant un détecteur de rayons infrarouges (104), et lesdits moyens de détection de position d'extinction comprenant en outre un capot (107) qui se projette en direction d'une position prédéterminée d'un côté latéral dudit rouleau de tabac, pour empêcher aux rayons infrarouges émis depuis l'autre partie dudit rouleau de tabac qu'une partie au niveau de ladite position d'extinction et au voisinage de celle-ci de pénétrer dans ladite tête de détection (91).
6. Appareil selon la revendication 5, caractérisé en ce que ledit capot (107) a une section transversale sensiblement semi-circulaire avec une surface semi-circulaire de celui-ci faisant face à ladite extrémité dudit rouleau de tabac (4).
7. Appareil selon la revendication 2, caractérisé en ce que lesdits moyens de découpe (36) comprennent une paire d'éléments d'ouverture/fermeture (32) prévus sur ladite main de manipulation (33) dudit robot de fonctionnement (31), chacun desdits éléments d'ouverture/fermeture (32) comprenant une lame de découpe (86) ayant une partie avant triangulaire qui s'étend vers l'autre élément d'ouverture/fermeture et qui est définie par un sommet et par deux bordures latérales des deux côtés dudit sommet, ledit sommet de l'un desdits éléments d'ouverture/fermeture étant agencé à l'opposé du sommet de l'autre élément d'ouverture/fermeture, lesdites parties avant triangulaires desdits éléments d'ouverture/fermeture étant agencées de manière à se recouvrir l'une l'autre, tandis que lesdits éléments d'ouverture/fermeture s'approchent l'un de l'autre.
8. Appareil selon la revendication 1, caractérisé en ce que des moyens d'évacuation de cendres (51, 52, 53, 55) sont prévus sous lesdites bouches à fumer (2) et comprennent un mécanisme de convoyage (51) ayant une courroie résistante à la chaleur qui circule horizontalement (53) et un réservoir à cendres (55) prévu sous une partie terminale distale dudit mécanisme de convoyage, pour recevoir les cendres et les bouts de tabac transportées par ledit mécanisme de convoyage.

9. Appareil selon la revendication 8, caractérisé en ce que ladite courroie (53) est réalisée avec une plaque de métal mince.

10. Appareil selon la revendication 1, caractérisé en ce que des moyens d'évacuation de fumée (60) sont prévus au voisinage dudit corps principal (1) et comprennent un capot d'évacuation de fumée (61) prévu au-dessus desdites bouches à fumer (2), pour recueillir la fumée auxiliaire qui s'élève depuis lesdits rouleaux de tabac montés dans lesdites bouches à fumer et en train de brûler, un ventilateur (63) pour déplacer ladite fumée auxiliaire recueillie dans ledit capot d'évacuation de fumée (61) vers le haut, et un mécanisme de levage de capot (62) pour déplacer verticalement ledit capot d'évacuation de fumée.

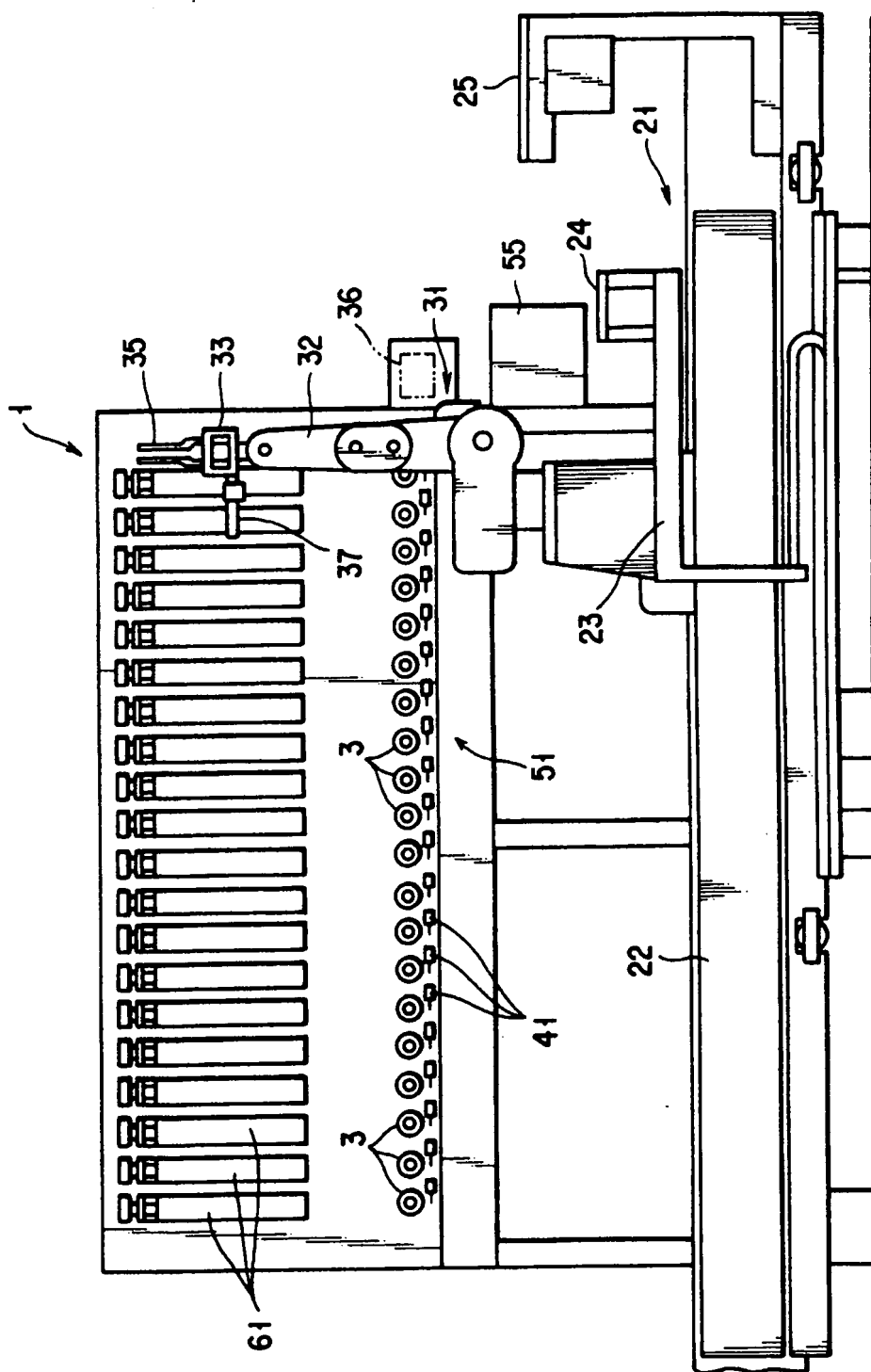


FIG. 1

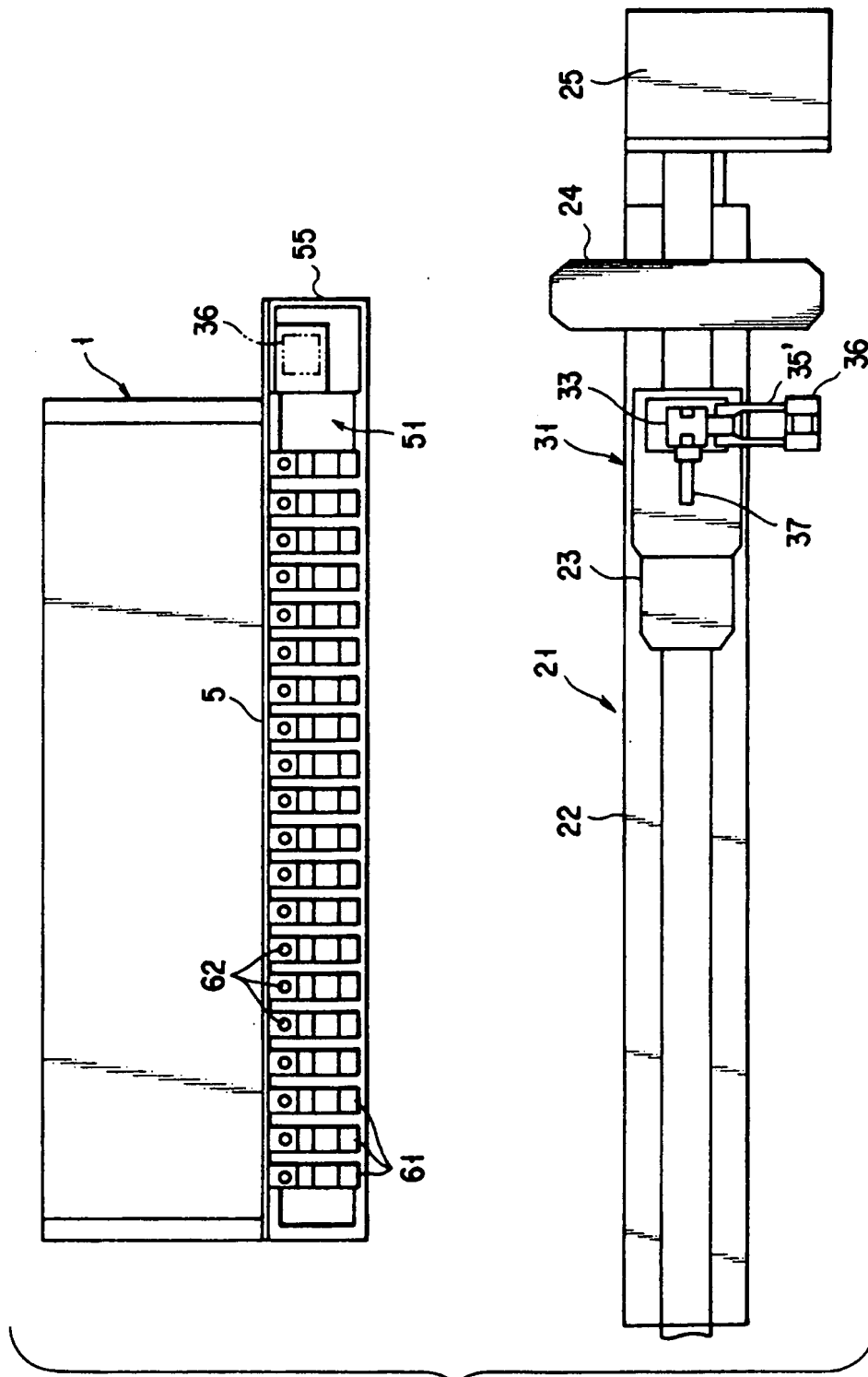


FIG. 2

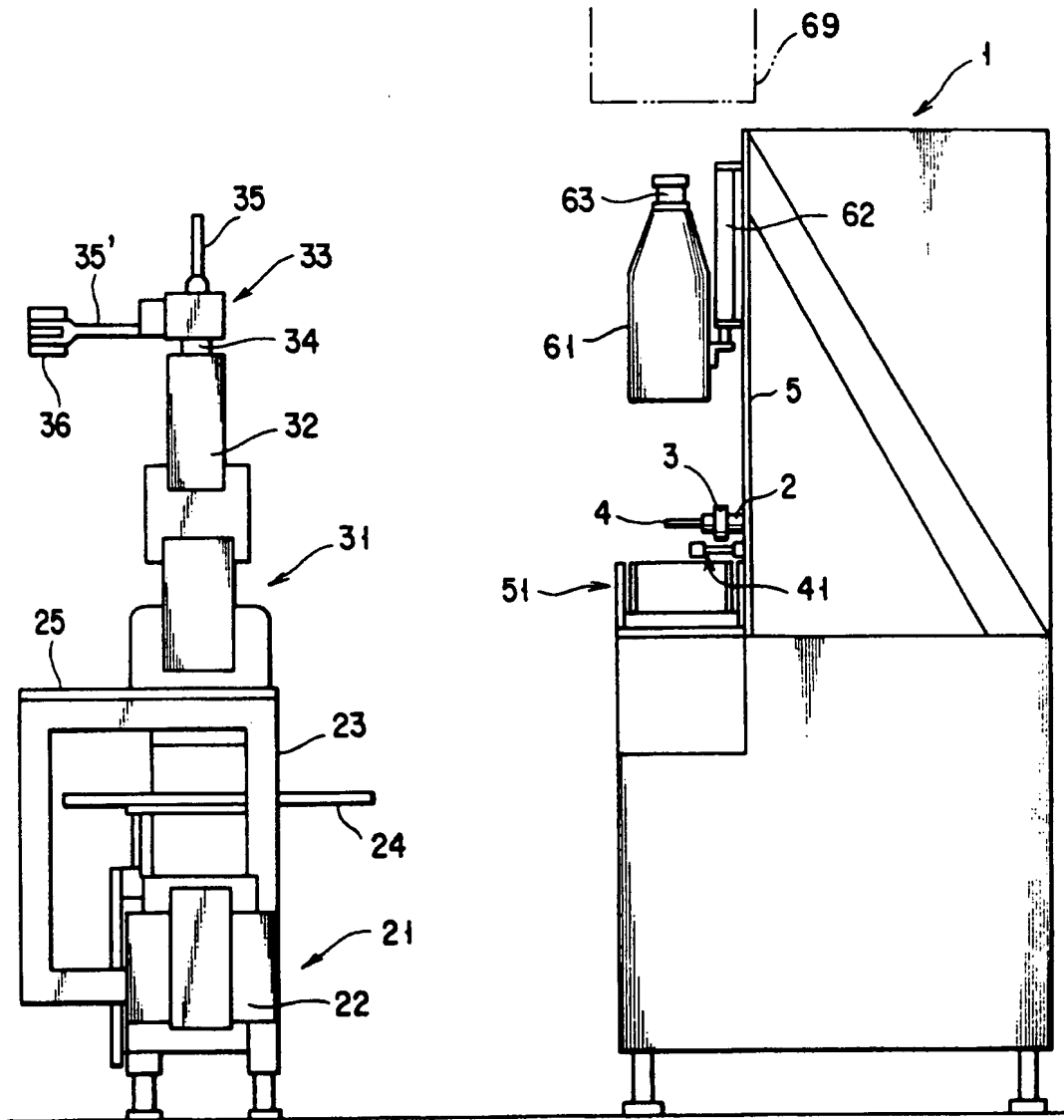


FIG. 3

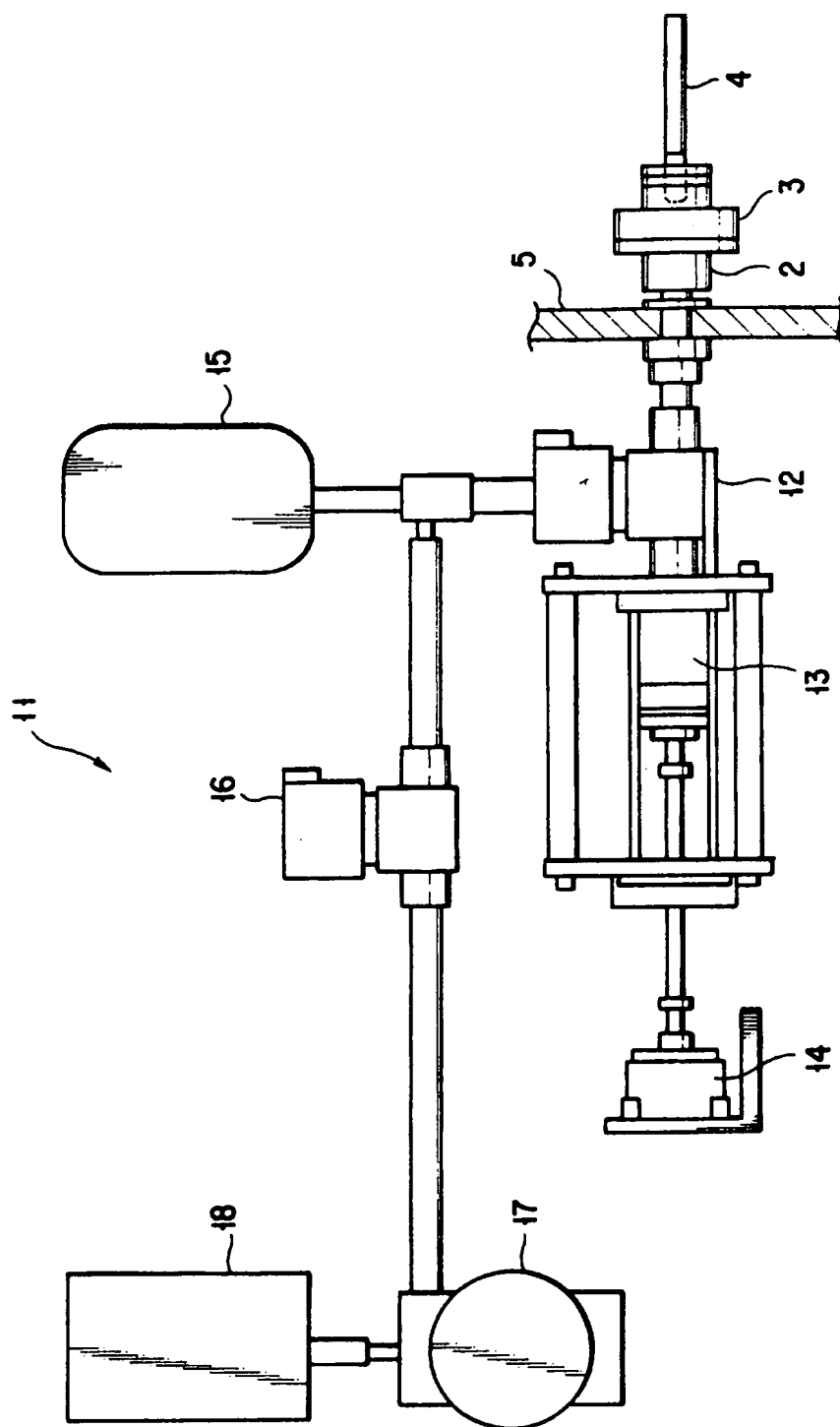


FIG. 4

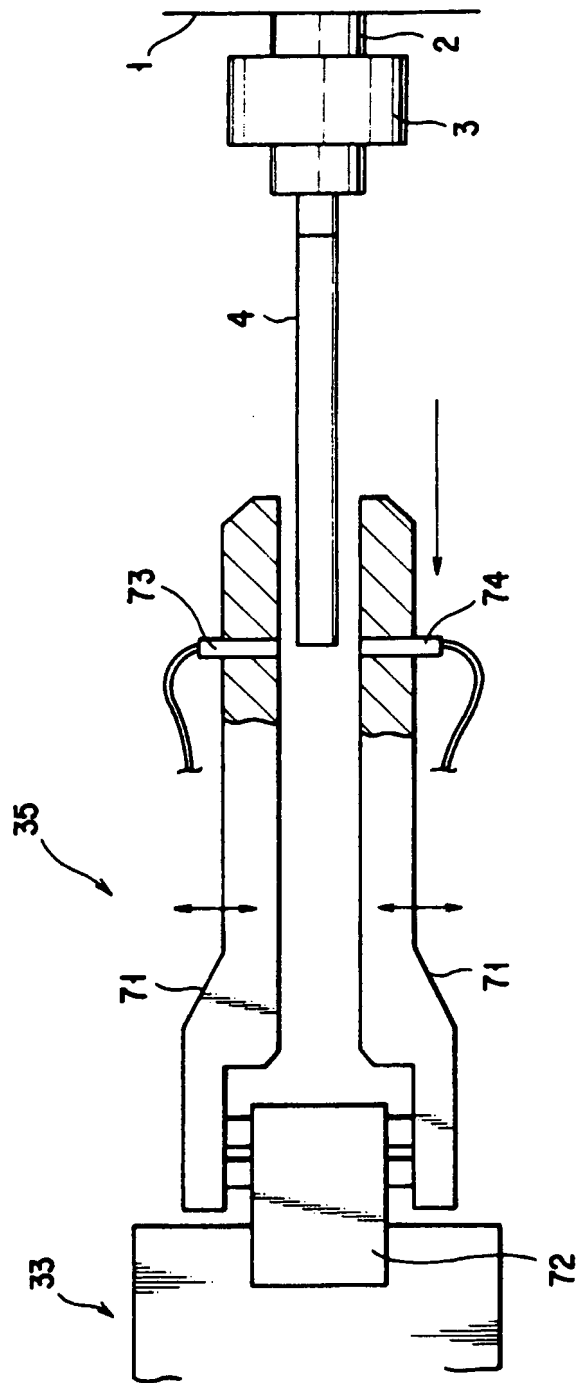


FIG. 5

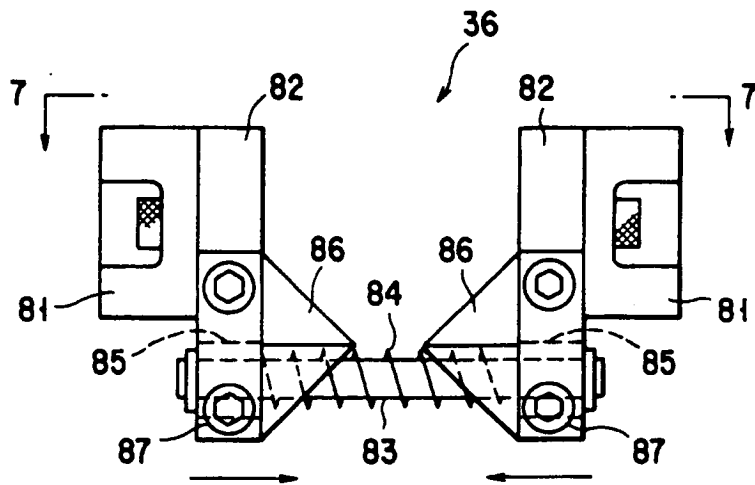


FIG. 6

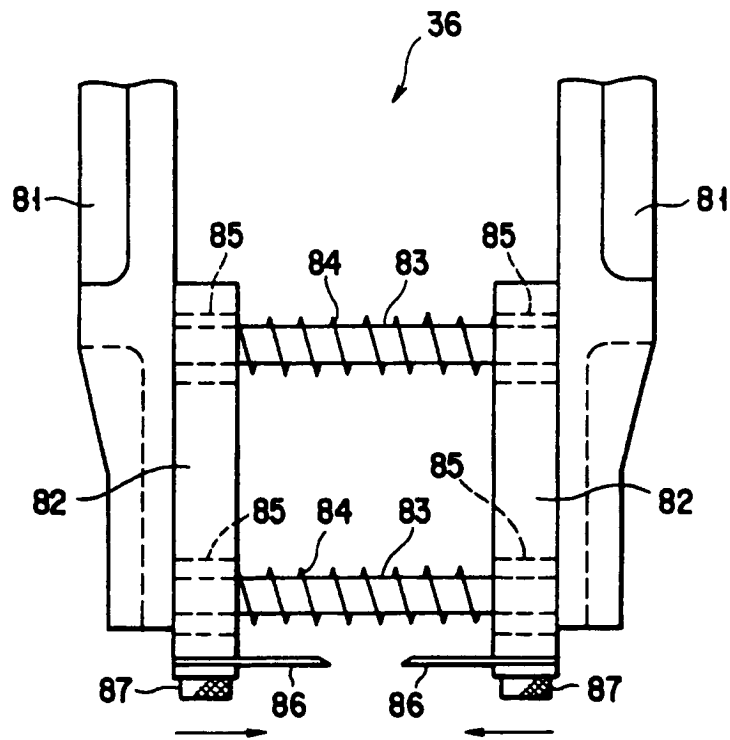


FIG. 7

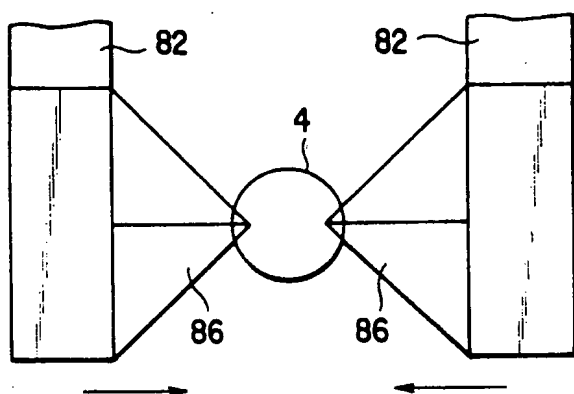


FIG. 8

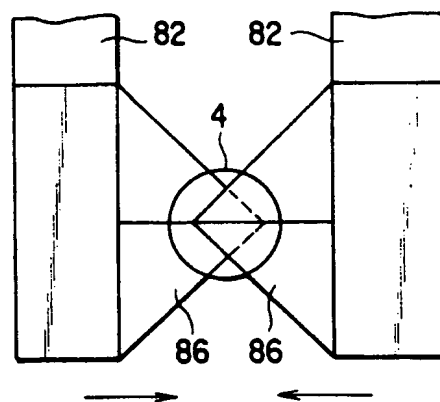


FIG. 9

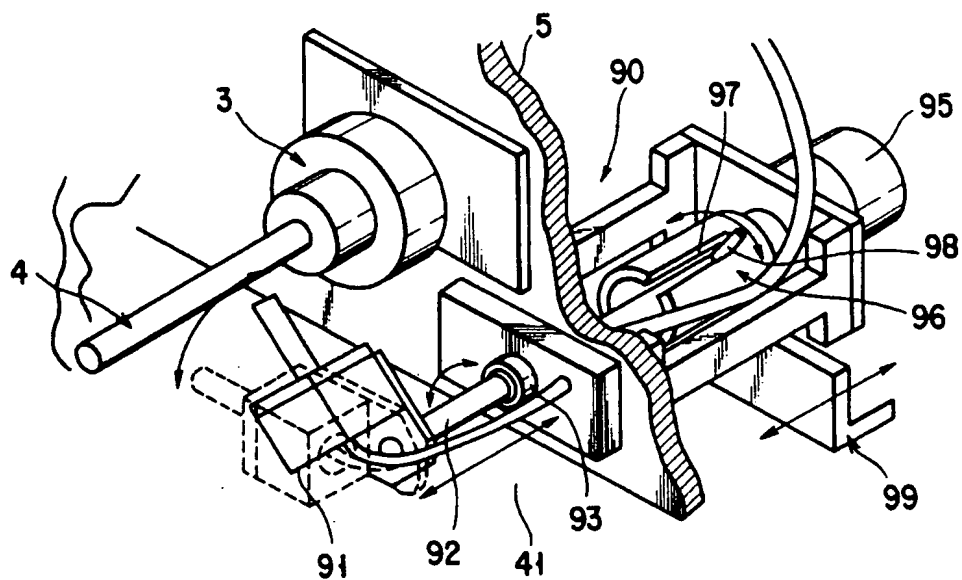


FIG. 10

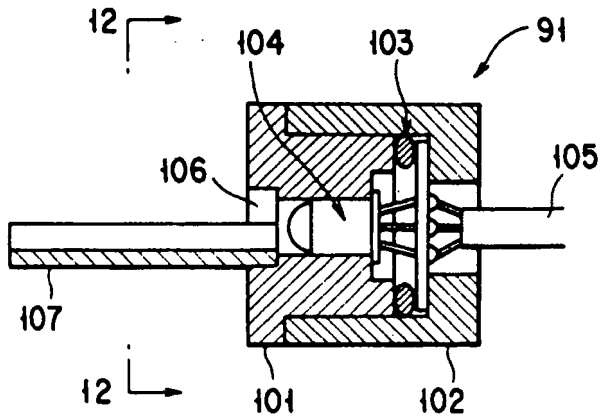


FIG. 11

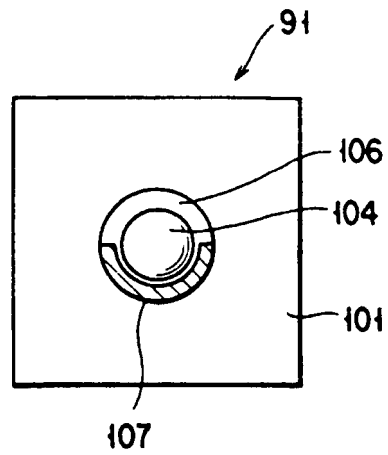


FIG. 12

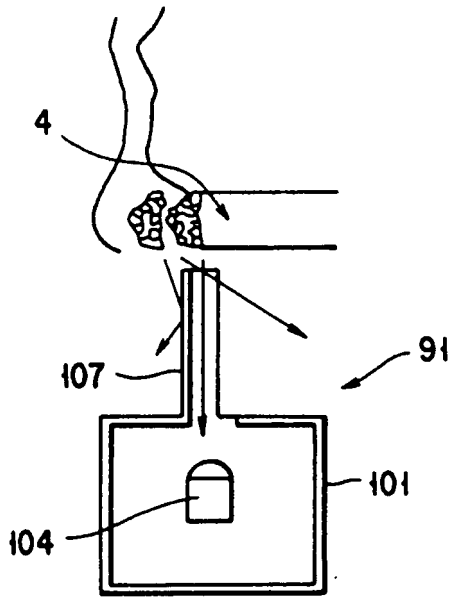


FIG. 13

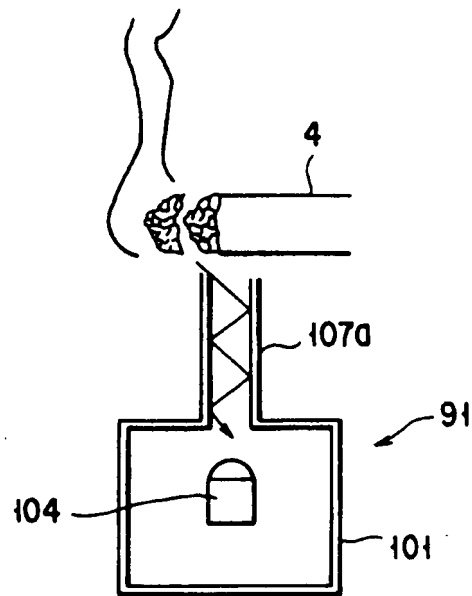
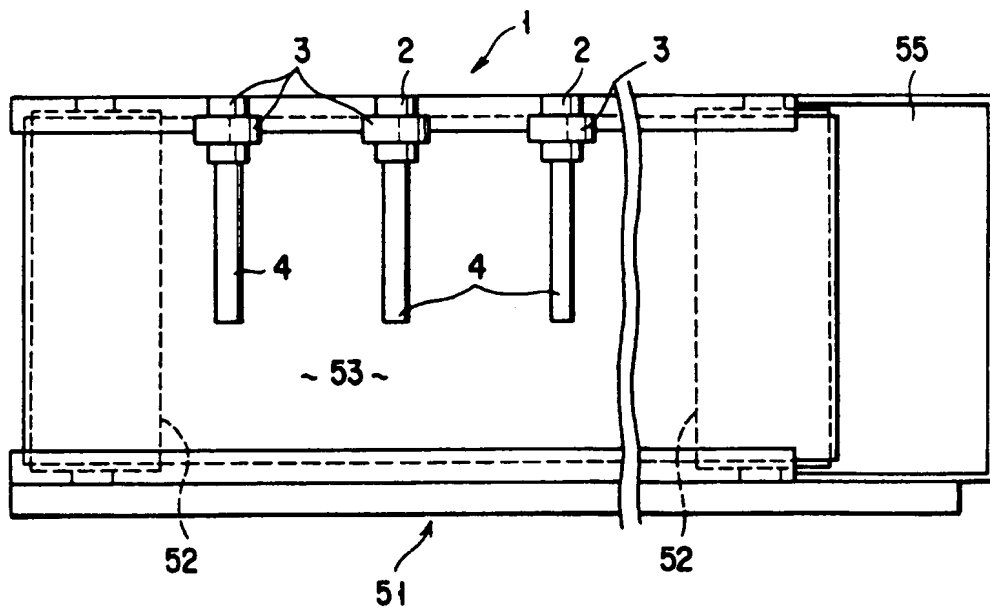
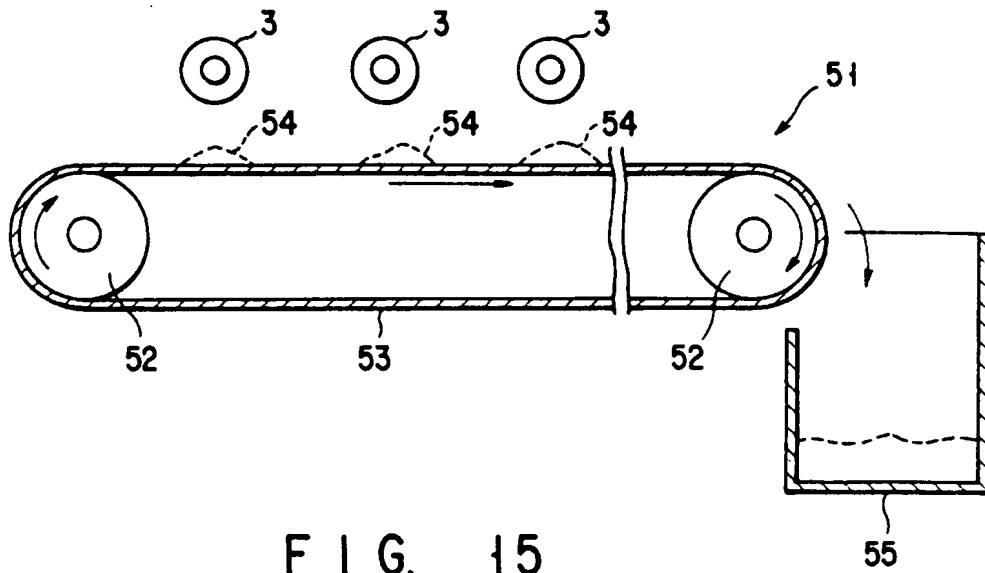


FIG. 14



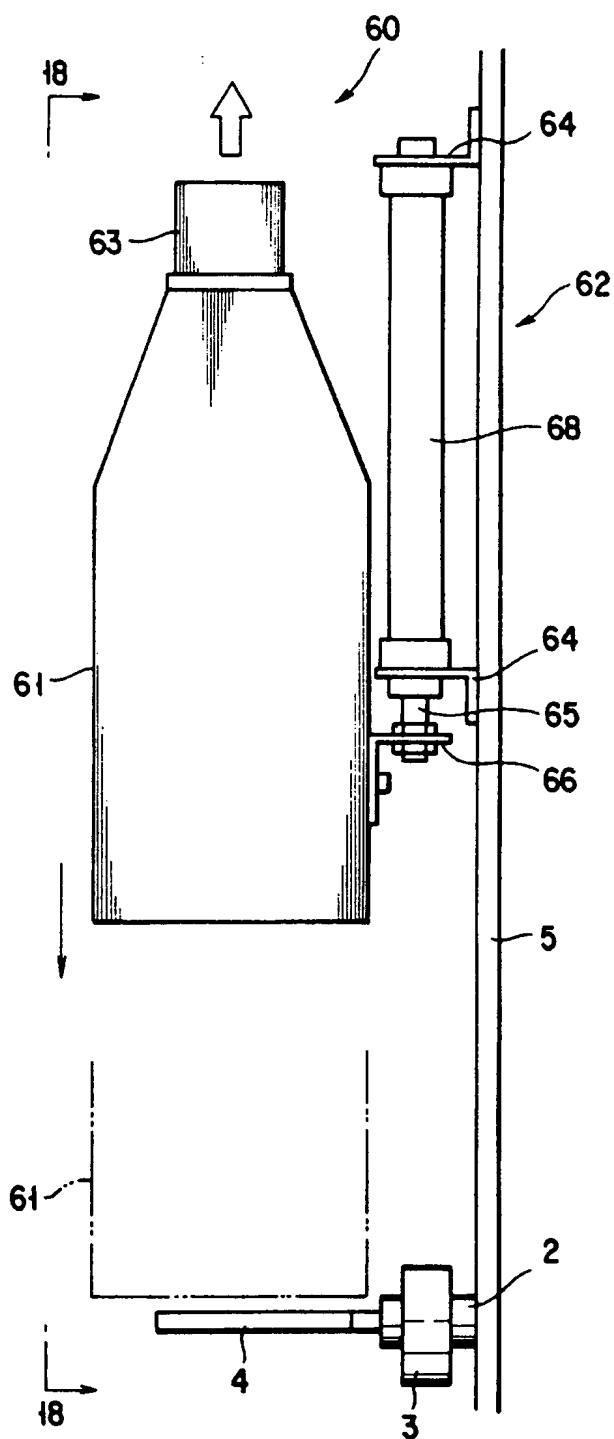


FIG. 17

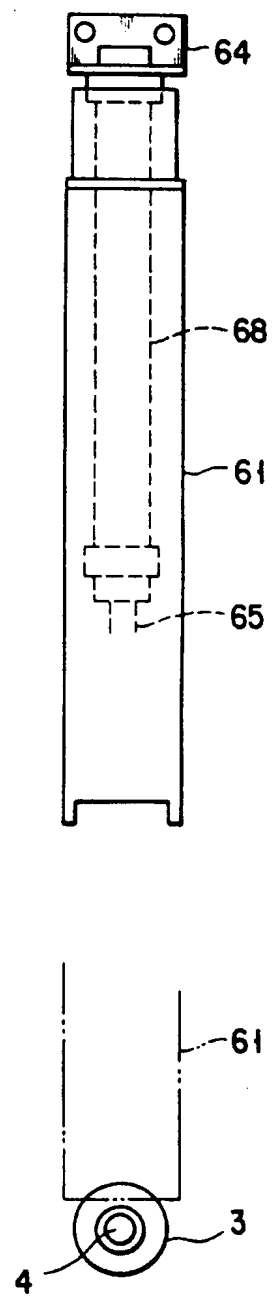


FIG. 18